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Impact of roadside conifers vegetation growth on air pollution mitigation

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Abstract

As a Nature-Based Solution, roadside green infrastructure (also known as roadside barriers) can potentially mitigate traffic-related air pollution by increasing dispersion and promoting pollutant deposition. For new and existing roadside barriers, the vegetation's physical and ecological attributes (dimensions and density) are dynamic in nature, and thus affect the barriers' pollution reduction capabilities. In this study, we first synthesized the results from existing field measurements characterizing the properties of coniferous vegetation, which show that its growth was characterized by an increase in height and a decrease in density. Motivated by this finding, a total of 75 simulations was conducted using a coupled aerodynamics and deposition model to investigate how the growth patterns of roadside vegetation barriers (e.g., heights from 2-10 m, and leaf area index (LAI) from 4-11) affects air pollutant reduction under different urban conditions (wind speeds 1-5 ms⁻¹). The results indicated that the ideal stage of maturity for the vegetation barrier to achieve the most pollutant reduction is from heights of 4-6 m. In this scenario, the vegetation barrier enhances pollutant deposition, has a moderate wake region, and generates a high level of turbulence that promotes downwind pollutant dispersion. It is imperative to account for growth patterns when selecting vegetation as roadside barriers to ensure that it can be maintained through pruning to achieve an ideal barrier height and optimal air pollutant reduction.

Keywords: Air quality, Green infrastructure, Urban green designs, Computational fluid dynamics (CFD), Nature-based solutions

1. Introduction

Exposure to traffic-related air pollution (TRAP) can cause negative health effects, including cardiovascular and respiratory diseases (HEI, 2010; Wilker et al., 2013). Over 45 million people in the U.S. have been estimated to live within 100 m of a major roadway (U.S. Census Bureau, 2009), with minorities and low-income residents more likely to reside at near-road environments (Tian et al., 2013). Millions more people live, work and go to school near large roadways worldwide.

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39 The use of Nature-Based Solutions or green infrastructure (GI) including vegetation to address
40 social and environmental issues is beneficial (Dorst et al., 2019). Roadside vegetation can help
41 alleviate this health burden by reducing TRAP and improving the local air quality in these
42 communities (Baldauf et al., 2008; Al-Dabbous and Kumar, 2014; Gallagher et al., 2015; Baldauf,
43 2017; Abhijith et al., 2017; Tiwari et al., 2019). However, the physical and ecological attributes of
44 vegetation can strongly influence their capability to reduce local TRAP (Lin et al., 2016; Tong et al.,
45 2016; Deshmukh et al., 2019). Vegetation can primarily reduce pollutants either through deposition,
46 as pollutants settle on the leaves of vegetation, or dispersion, as vegetation alters the airflow around
47 it causing pollutants to dilute (Janhall, 2015). An increased density of vegetation enhances deposition
48 and promotes stronger downwind dispersion (Ghasemian et al., 2017; Deshmukh et al., 2019; Hashad
49 et al., 2020). Vegetation dimensions (width and height), density characteristics leaf area density
50 (LAD) and leaf area index (LAI) influence the capacity to improve air quality downwind of the barrier
51 (Tong et al., 2016; Deshmukh et al., 2019).

52 For newly planted and existing barriers, the impact of vegetation is dynamic as it will continue to
53 grow over time, leading to spatiotemporal effects linked to its physical and ecological attributes
54 (Bartesaghi-Koc et al., 2020; Corada et al., 2021). While urban planners and local communities can
55 control the barrier's physical characteristics through active maintenance and pruning, no clear best-
56 practice recommendations exist on how to do so while achieving optimal pollutant reduction. It is
57 imperative to understand how vegetation growth over time affects its capability to mitigate TRAP.
58 Only coniferous vegetation is considered since it has less seasonal variation (maintaining similar leaf
59 area density and therefore pollutant reduction performance throughout the year) and it provides leaf
60 cover from ground level upwards (preventing pollutant to pass unobstructed at ground level). Whereas
61 broadleaf vegetation can lose their leaves in the winter making them ineffective at pollutant reduction,
62 and some broadleaved species have long trunks that might allow pollutants to pass through them
63 unfiltered. Lin et al., 2016 conducted field measurements that showed that vegetation barriers with
64 full foliage reduced ultra-fine particle concentration by 37.7-67.7%, but measurements at the same
65 site during wintertime, when the foliage was reduced, showed no significant change in UFP
66 concentrations. Therefore, broadleaf vegetation that loss their leaves during the winter should not be
67 considered for roadside barriers that are meant to mitigate air pollution year-round. Instead, conifers
68 or evergreen vegetation, which are the focus of this study, should be considered as they are not subject
69 to significant seasonal change (Baldauf 2017). Previous studies of conifers species provide an insight
70 to the impact of vegetation growth on its physical and ecological properties, as its height increases
71 (Pokorney et al. 2008; Malek et al. 2012, Vose et al., 1994). These studies suggest that certain
72 vegetation's LAD can decrease by more than a factor of 5, and its height increase by 7-11 m, over a
73 period of 10-15 years, therefore a vegetation barrier will experience substantial change over time due
74 to vegetation growth.

75 Stakeholders implementing roadside vegetation barriers to mitigate TRAP must understand the
76 long-term implications of vegetation growth on near-road pollution. This can help urban planners and
77 local communities make informed decisions when designing, planting, and maintaining vegetation
78 barriers. Field measurement studies primarily focus on assessing existing vegetative barriers and how
79 they reduce pollutant concentration. Most of the field measurements usually take place over a period
80 of days or weeks (Lee et al., 2018, Xing and Brimblecombe 2019, Ranasinghe et al., 2019). A few
81 field measurements were conducted over a longer duration (3-5 months) to address the impact of
82 seasonal change on vegetation and TRAP reduction (Lin et al., 2016; Ottosen and Kumar, 2020). In

83 addition, site specific variations relating to the physical and environmental conditions of a vegetation
84 setting require multiple monitoring setups over long time periods. Relying on field measurements
85 alone to assess the impact of vegetation growth on pollutant reduction and develop best-practices in
86 vegetation maintenance is resource intensive and challenging due to varying climate conditions.
87 Computational fluid dynamics (CFD) offers an alternative method to evaluate vegetation barrier
88 designs, under various urban conditions, to understand their impact on near-road air quality (Tong et
89 al., 2016; Santiago et al., 2019; Hashad et al., 2020, Rafael et al. 2018, Li et al., 2022).

90 To the best of our knowledge, there are no studies that investigated the long-term impact of
91 vegetation growth on pollutant reduction. The objective of this study is to determine how roadside
92 vegetation growth affects the physical mechanisms by which the barrier reduces pollutants through
93 dispersion and deposition. To address that, we first performed a thorough synthesis of existing field
94 studies that examine coniferous vegetation at different ages and characterizes its properties, such as
95 dimensions and density, to understand how vegetation growth impacts its properties, and is presented
96 in Section 2.2. Then, motivated by the key finding from the synthesis we conducted 75 high-fidelity
97 CFD simulations, using the Comprehensive Turbulent Aerosol Dynamics and Gas Chemistry (CTAG)
98 model (Wang et al., 2011; Wang and Zhang, 2012; Wang et al., 2013). The CTAG model has been
99 previously validated against various field measurement studies to ensure that it can properly capture
100 both the aerodynamic and deposition impacts of the vegetation barrier (Steffens et al., 2012; Tong et
101 al., 2016; Hashad et al., 2020) and is discussed in more detail in Section 2.5. The 75 simulations
102 reflect coniferous vegetation barriers in an open-road condition, at various growth stages, with heights
103 ranging from 2-10 m and leaf area index (LAI) varying from 4-11, in order to study their pollutant
104 reduction capabilities. Simulations were undertaken for five different wind speeds ($1-5\text{ ms}^{-1}$) to reflect
105 various urban meteorological conditions. Furthermore, various pollutant particle sizes were modelled
106 to account for traffic exhaust pollution reductions as pollutant deposition on vegetative surfaces, e.g.,
107 leaves, is particle size-dependent. Additionally, the downwind spatial decay was analyzed to
108 understand the influence of the barrier on the downwind dispersion of concentrations.

109 This paper is organized as follows. Section 2 describes how vegetation growth impacts its
110 properties, the vegetation representation in our simulation, the CTAG model, and the computational
111 domain used in this study. Section 3 discusses the physical mechanisms, by which the various barriers
112 disperse pollutants, and analyze their respective pollutant reduction. Finally, Section 4 is the
113 conclusion.

114

115 **2. Methods**

116 In this section, we first describe two important vegetation parameters that affect the barrier's
117 pollutant reduction which are the leaf area density (LAD) and the leaf area index (LAI). Then, we
118 present a synthesis of several field measurement studies that document vegetation properties (LAD,
119 LAI, and dimensions) at different ages to understand how vegetation growth affects its characteristics.
120 The results from the synthesis were used to constrain the 75 LES model scenarios highlighted in this
121 study that reflect coniferous vegetation at different ages to understand the influence of vegetation
122 growth on pollutant reduction. The computational approach is then presented, including a description
123 of the domain and boundary conditions, the CTAG model used, how vegetation is represented in the
124 model, and the CTAG model evaluations. Finally, the evaluation criteria used to assess the various
125 vegetation barriers at different growth stages is highlighted. An overview of the Methods section and
126 how it is organized is displayed in Figure 1.

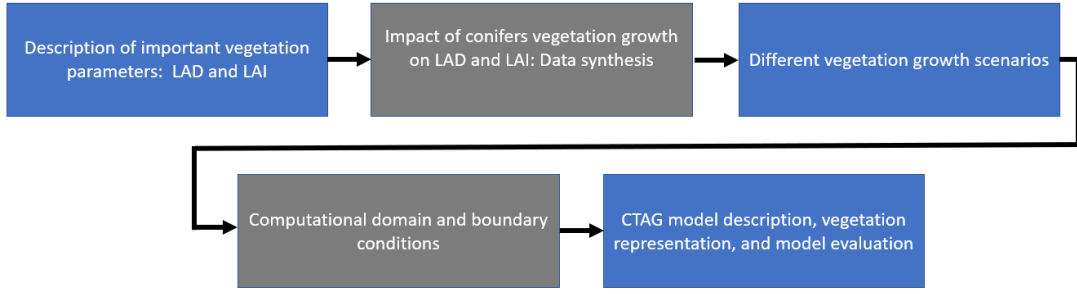


Figure 1: Overview of the methods section

2.1. Vegetation leaf area density (LAD) and leaf area index (LAI)

Vegetation LAD and LAI are two key properties that will influence the pollutant reduction of the vegetation barrier, and it is beneficial to understand how vegetation growth influences them. LAD is a measure of the surface area of leaves per unit volume within the vegetation, units $\left(\frac{m^2}{m^3}\right)$, and it is an important property affecting vegetation deposition and drag. The LAD profile for coniferous vegetation was considered in this study and can be described by Equation 1 (Lalic and Mihailovic, 2004):

$$LAD(z) = L_m \left(\frac{h - z_m}{h - z} \right)^n \exp \left[n \left(1 - \frac{h - z_m}{h - z} \right) \right],$$

$$\text{where } n = \begin{cases} 6 & 0 \leq z \leq z_m \\ 0.5 & z_m \leq z \leq h' \end{cases} \quad (1)$$

L_m is the maximum LAD within the vegetation, z is the height, z_m is the height at which L_m occurs ($z_m = 0.4h$), and h is the vegetation height. This LAD profile has also been used in other CFD modelling studies (Li and Wang, 2018, Xing et al., 2019).

Vegetation leaf area index (LAI) is a unitless metric used to characterize vegetation canopies, defined as the projected area of leaves per ground surface area. If the height and LAI of vegetation is known, the peak LAD, L_m , can be evaluated using Equation 2:

$$LAI = \int_0^h LAD(z) dz \quad (2)$$

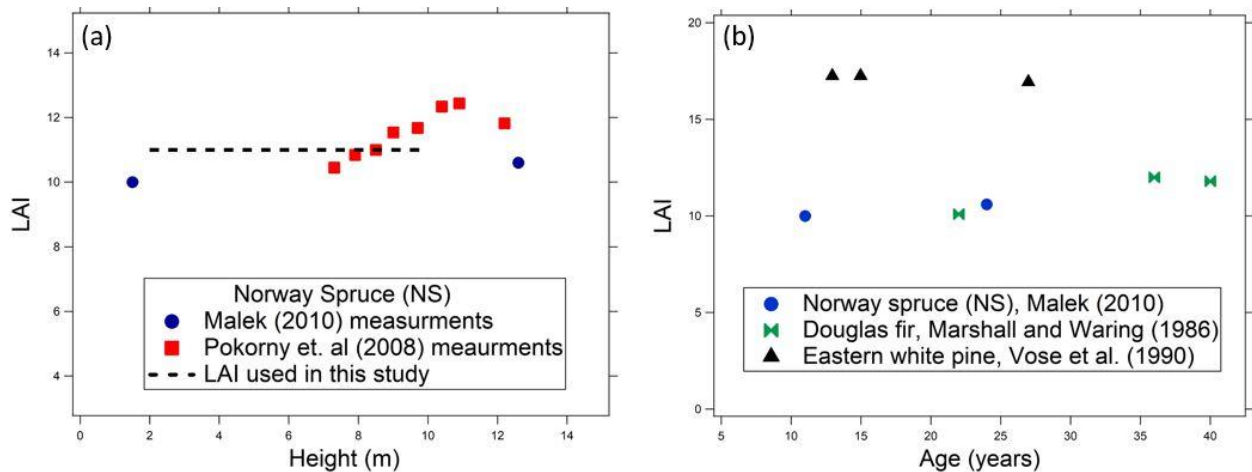
2.2. Impact of vegetation growth on LAI and LAD: Data Synthesis

Understanding how the LAI changes with vegetation growth is important in understanding the mitigation potential of vegetation barriers. We analyzed studies that provided estimates of the LAI for various coniferous vegetation at different ages either through monitoring them over a couple of years as they grow or examining already existing coniferous stands of different ages. Vegetation growth can be described in three growth phases. In the first phase, the vegetation is young and its LAI increases during stand development, as the vegetation crown expands. It reaches its peak LAI during early canopy closure, i.e., when the crowns or canopies of individual trees overlap to form a continuous layer. Fast-growing species can reach their peak LAI in 10-15 years, while slow growing species can reach their peak after 20-40 years (Vertessy et al., 2001; Pokorny and Stojnic, 2012).

156 Factors such as the local climate, soil type and nutrient availability will affect how fast the vegetation
 157 develops. The second phase occurs after this peak, as the LAI decreases to some maximum average
 158 LAI that is maintained for years due to canopy closure, competition with other trees, and reduced
 159 foliage development (Pokorny et al., 2008; Vose et al., 1994). The third phase occurs when the
 160 vegetation ages and its LAI eventually starts to decrease as Pokorny and Stojnic (2012) highlighted
 161 that the maximum LAI values of spruce stands decreased by 30%, from 12.8 to 8.4, between their
 162 peak at 15-20 years to 120 years, due to aging factors (vegetation tissues aging, decreased nutrient
 163 supply, and crown abrasion from space competition) (Ryan et al., 1997). In this study, we focused on
 164 vegetation in their second development phase, since they reach their peak LAI and achieve canopy
 165 closure which is necessary to ensure that it is an effective roadside barrier with no gaps.

166
 167 Figure 2 and Table 1 highlight the LAI versus vegetation attributes (height of Norway Spruce and
 168 age for other conifer species) for vegetation in their second development phase demonstrating that
 169 the LAI experiences little change over a substantial age and height range in that stage. The vegetation
 170 barriers explored in this study reflect young conifers, Norway Spruce, of heights between 2-10 m and
 171 over an 11-year growth period (12-23 years), which is reflected in Figure 2a, and is realistic for
 172 roadside barrier applications as highlighted in later sections. In this case, any decrease in the LAI due
 173 to aging is not significant. Malek (2010) and Pokorney et al. (2008) showed that the LAI for Norway
 174 Spruce increased by a maximum of 0.9-1.6% per year during that growth period (Figure 2a and Table
 175 1). The outcome was similar for trees planted in rows and forest stands, therefore the findings can
 176 translate to densely planted vegetation barriers in near-road environments. Due to this small change
 177 over a long growth period, a constant LAI of 11 was assumed for the different barriers considered in
 178 this study, which aligns with past studies (Pokorny and Stojnic, 2012; Gower and Norman, 1991).
 179 Figure 2b and Table 1 also show that other studies found uniform LAI patterns were attained after
 180 the peak value for different conifer species such as pine and fir and therefore is a reasonable
 181 assumption (Vose et al., 1994; Marshall and Waring, 1986; Zhao et al., 2011; Kim et al., 2017;
 182 Barclay et al., 2000; Turner et al., 2000).

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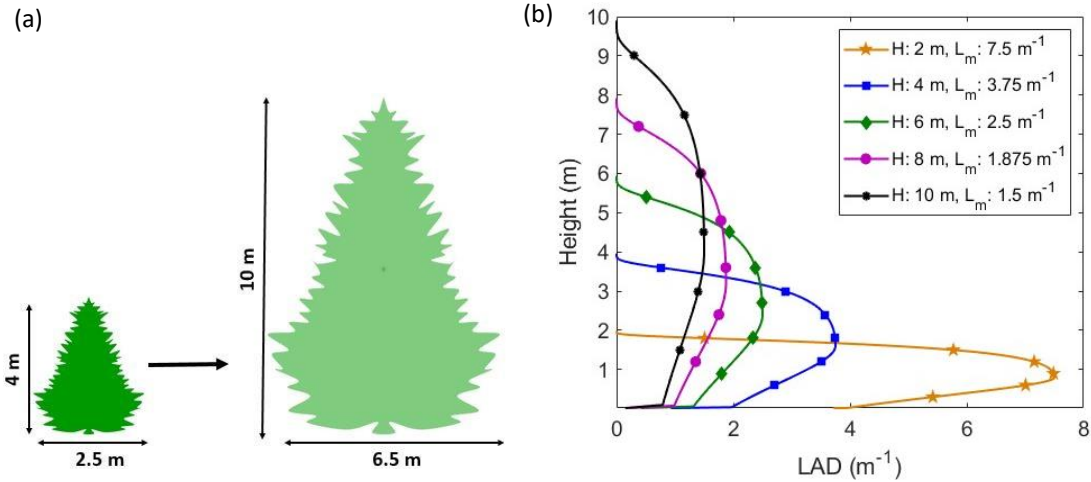


185
 186 Figure 2: Details of (a) LAI versus vegetation height for Norway Spruce from previous studies
 187 compared to LAI value used in this study; and (b) LAI development over time for various coniferous
 188 species, which indicates that species maintain a steady LAI after reaching peak LAI.

Table 1: LAI for various conifers species at different ages and heights

Conifers species	Height (m)	Age (years)	LAI	References
Norway spruce	7.3		10.5	Pokrony et al. (2008)
	7.9		10.8	
	8.5		11.0	
	9.0		11.5	
	9.7		11.7	
	10.4		12.3	
	10.9		12.4	
	12.2		11.8	
Norway spruce	1.5	11	10.0	Malek (2010)
	5	16	10.2	
	12.6	24	10.6	
	16.2	29	10.6	
Douglas-fir		22	10.1	Marshall and Waring (1986)
		36	12.0	
		40	11.8	
Eastern white pine		13	17.2	Vose and Swank (1990)
		15	17.3	
		27	16.9	
Balsam fir	14.4	23	9-11.3	Derose and Seymour (2010)
	13	29	9.5-12.1	
	15	40	8.3-10.9	
Douglas fir		20-80	10.6	Turner et al. (2000)
		20-80	9.2	
		20-80	12.2	
Douglas fir		24	9.6	Barclay et al. (2000)
		33	13.2	
		48	11.4	
Norway spruce		28	9.88±0.92	Homolova et al. (2007)

192 Since the LAI for vegetation does not substantially change for the explored height range, this
193 implies that as the height of the vegetation increases, the overall density within the vegetation will
194 decrease as highlighted in Figure 3a. Figure 3b shows the LAD profiles of dense vegetation (LAI =
195 11) for all heights simulated in this study, which indicates that shorter vegetation is denser compared
196 to taller vegetation. The LAD experiences substantial change, which will influence the vegetation
197 pollutant reduction capabilities as discussed in the results section.



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Figure 3: A schematic of (a) the small and large vegetation layouts considered in this study, its LAD decreases as reflected by the faded color representing vegetation density; and (b) the LAD profile for all the dense vegetation (LAI = 11) cases evaluated in this study, where l_m is the maximum LAD that occurs at height $z = 0.4h$. As the vegetation grows in height its LAD decreases.

204 *2.3. Vegetation dimensions and simulated cases*

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We investigated vegetation barriers, growing from heights 2 to 10 m, as vegetation shorter than 2 m might not have reached its optimal LAI (still developing) and might allow pollutants emitted by nearby cars and trucks to pass above it, and vegetation taller than 10 m might be challenging to plant and maintain safely for roadside applications. The barrier used in this study consists of two rows of a single type and species of vegetation to reduce any gaps within the barrier. The width (crown length) to height ratio for a single tree was 2/3 reflective of typical coniferous vegetation (Tahvanainen and Forss, 2008; Garber et al., 2009), and has been used in other modelling studies (e.g., Katul et al., 2004). The total barrier width to height ratio was 4/3 since it consisted of two rows of vegetation. Table 2 displays the fifteen different vegetation barrier configurations considered in this study and reflect the barrier at five distinct growing stages (heights 2 – 10 m), and three different densities as represented by the LAI values 4, 7, and 11 to investigate the impact of vegetation growth for various conifers vegetation species with different densities. That ensures that our results not only consider dense conifers like Norway spruce and Douglas fir (LAI = 11), but also other species that might have lower densities (LAI = 4 or 7) (Fassnacht 1997). However, the primary analysis in this study focused on vegetation with an LAI of 11, representing dense conifers, since they are effective roadside barriers compared to less dense vegetation as highlighted later in Section 3.5.

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The age and growth rate (0.75 m per year) used in this study were based on the average growth rates of Norway Spruce in those studies (Pokorny et al., 2008; Malek, 2010). The age was rounded to the nearest year, and it is important to note that the age at which vegetation reaches a certain height will depend on several factors such as species, local climate, soil properties, and availability of nutrients (Vose et al., 1994). Therefore, the height and LAI values of the vegetation are better metrics to select vegetation barriers as opposed to age and it can also be applicable to various species that might have different growth rates. Table 2 lists the properties for each barrier configuration, which include the age, height (H), width (W), LAI, and peak LAD (L_m). Each case was tested under five different wind speeds at a height of 10 m (1, 2, 3, 4, and 5 ms^{-1}) to account for various urban conditions, hence 75

230 total simulations. In addition, 5 simulations were conducted with no barrier at the respective wind
 231 speeds to normalize the results.

232 Table 2: Vegetation barrier properties at various growth stages

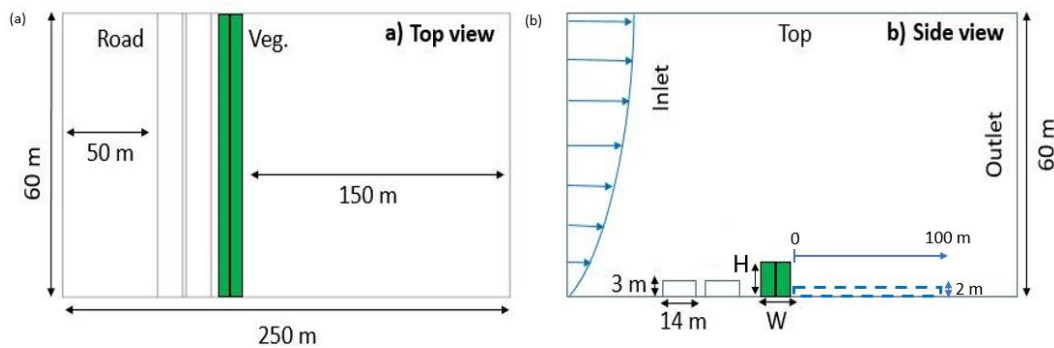
Age (Years)	H (m)	W (m)	L_m (m^{-1})		
			LAI=11	LAI=7	LAI=4
12	2	2.5	7.50	4.82	2.75
15	4	5.0	3.75	2.41	1.38
17	6	8.5	2.50	1.60	0.92
20	8	10.5	1.88	1.20	0.69
23	10	13.0	1.50	0.96	0.55

233

234 *2.4. Computational domain and boundary conditions*

235 Figure 4 displays a schematic of the top and side views of the computational domain for this
 236 study. The dimensions of the domain were 60 m along the roadway driving direction, 60 m in the
 237 vertical direction, and 250 m in the downwind direction. To represent traffic emissions, two zones of
 238 height 3 m and width 14 m each, were used as pollutant sources reflective of a two-way 4 lane traffic
 239 bound. A height of 3 m was chosen to account for the initial dispersion of pollutant due to vehicle
 240 motion and induced turbulence (Hashad, 2017). This is consistent with other studies that used a traffic
 241 zone height of 2.4-3 m (Amorim, 2013; Zheng, 2022). To model vegetation, two zones were created
 242 highlighting both rows of vegetation. The vegetation dimensions (height and width) and
 243 characteristics (LAD) depend on the simulated case as discussed in the previous sections. The tallest
 244 vegetation barrier considered was 10 m, therefore a domain height of 60 m, five times greater than
 245 the vegetation height, was selected to ensure no unphysical flow acceleration or blocking effects
 246 (Tominaga et al., 2008). The guidelines recommended in Blocken (2015) were followed so a spacing
 247 of 5H upstream of the road and a spacing of 15H downwind of the vegetation barrier was used to
 248 properly capture the pollutant dispersion of the barrier (Figure 4a). A uniform mesh, with an average
 249 cell size of 0.492 m and all hexahedral elements (total of approximately 7.5 million cells), was used
 250 as highlighted in Figure S1. A mesh independence study showed that a refined mesh, with a cell sizing
 251 of 0.38 m and a total of 14.7 million cells, had little sensitivity with the mesh used, indicating that it
 252 captures most of the turbulent kinetic energy (TKE) in the domain (Figure S2).

253



254 Figure 4: A sketch of the computational domain used in this study a) Top view; b) Side view. The
 255 concentrations were averaged from a height of 0-2m starting from behind the vegetation barrier to
 256 100 m downwind of the barrier.
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259 The applied boundary conditions were a neutral atmospheric boundary layer (NABL) velocity
260 profile at the inlet, pressure outflow at the outlet, and symmetry at the top and sides of the domain.
261 To simulate the NABL at the inlet, the velocity described by Equation 3 was used (Richards, 1993):

262

$$U(z) = \frac{u_*}{k} \ln\left(\frac{z}{z_o}\right) \quad (3)$$

263 where U is the velocity, z is the height at which the velocity is evaluated, u_* is the frictional velocity,
264 k is the von Karman constant (=0.4), and z_o is the roughness height (=1 m). In all the simulations, the
265 wind is perpendicular to the barrier to account for the worst-case condition where the community is
266 expected to be exposed to the highest pollutant concentrations. The CTAG model was implemented
267 in this study and is described in the following Section.

268 2.5. CTAG model description, vegetation representation, and model evaluation

269 2.5.1 CTAG model description

270 The CTAG model was designed to resolve the flow field including turbulent reacting flows,
271 aerosol dynamics, and gas chemistry in complex urban environments (Wang et al., 2011; Wang and
272 Zhang, 2012; Wang et al., 2013). Large Eddy Simulations were used to resolve the fluid flow and we
273 implemented the dynamic Smagorinsky model to account for the subgrid turbulent viscosity
274 (Germano et al., 1991). The semi-implicit method for pressure linked equation (SIMPLE) algorithm
275 was used to couple the velocity-pressure equations, and a second-order upwind discretization scheme
276 was utilized for all the governing equations.

277

278 2.5.2 Vegetation drag and particle deposition in the CTAG model

279 The CTAG model used is consistent with that of our previous studies on roadside vegetation
280 (Steffens et al., 2012; Tong et al., 2016; Hashad et al., 2020). Since it is computationally expensive
281 to explicitly model the elements of vegetation like branches and leaves, the effects of vegetation on
282 the air flow are spatially averaged and accounted for by adding appropriate sink and source terms to
283 the governing equations (Wilson and Shaw, 1977). To account for vegetation drag, a sink term was
284 included in the momentum equations (Shaw and Schumann, 1992):

285

$$S_i = -\rho C_d L(z) U u_i \quad (3)$$

286 Where S_i is the sink term, $C_d (= 0.3)$ is the plant drag coefficient, $L(z)$ is the LAD profile, U is the
287 total velocity of the flow, and u_i is the velocity in the direction of interest.

288 Based on near-road and on-road measurements, nine different particle sizes, ranging from 15 to
289 253 nm, were included to reflect traffic exhaust emissions (Kittelson et al., 2004; Zhu et al., 2002;
290 Hagler et al., 2012). Since the evaluated particle sizes are small, they were assumed to act as tracers
291 to the flow, hence a one way coupling between the fluid and particles was used. The model did not
292 account for any particle transformation processes, including coagulation, as Steffens et al. (2012)
293 showed that it had a minor impact on pollutant particle size due to their short residence time. A scalar

294 transport equation was used to model pollutant dispersion and deposition. Equation 4 displays the
295 sink term included to the scalar transport equation to account for deposition.

$$296 \quad S_d(D_p) = \rho V_d(D_p) N_p(\overline{D_p}) L(z) \quad (4)$$

297 Where $N_p(\overline{D_p})$ is the average particle concentration of a particle size D_p , and $V_d(D_p)$ is the deposition
298 velocity adopted from the dry deposition model developed by Zhang et al. (2001). Furthermore, we
299 simulated a tracer gas that does not experience deposition or chemical reactions to capture the effects
300 of barrier on pollutant dispersion. This tracer gas adopted the physical properties of CO but setting
301 the deposition velocity to be zero. The main purpose of using a tracer gas in our simulations was to
302 provide a worst-case scenario, i.e., no reduction by vegetation and we can isolate the effect of
303 dispersion from deposition. The full governing equations for momentum, scalar transport, and
304 deposition velocity are provided in the Section S2 of SI.

305 2.5.3 CTAG model evaluation

306 Steffens et al. (2012) assessed the CTAG model using Reynolds-Averaged Navier-Stokes (RANS)
307 simulations against field measurements of both wind speed and particle size distribution, measured
308 behind a near-road vegetative barrier with 6-8 m tall coniferous tree species (Hagler et al., 2012). The
309 field measurements included wind speed data collected at heights 3 and 7 m and 3 m downwind of
310 the barrier, along with ultra-fine particle (UFP) size distributions, ranging from 12.6 to 289 nm. Tong
311 et al. (2016) later evaluated the CTAG model, using LES, against the same field measurements
312 showing better agreement than RANS, since LES better captured the impact of vegetation on the flow.
313 Hashad et al. (2020) also assessed the aerodynamic performance of the CTAG model, using LES
314 against wind speed data collected within and above a maize canopy (Pan et al., 2014) up to twice the
315 height of the canopy. The mean velocity and mean Reynolds stress predicted by the CTAG model
316 reasonably matched those reported in Pan et al. (2014). Section S3 in the SI provides a more detailed
317 description of the field measurements used to evaluate the CTAG model along with a comparison of
318 the CTAG model performance using RANS and LES versus field measurements from our previous
319 studies (Steffens et al. 2012, Tong et al., 2016, Hashad et al., 2020). The evaluation includes particle
320 size distributions, deposition velocities, and fluid flow parameters like mean speed and Reynolds
321 stress.

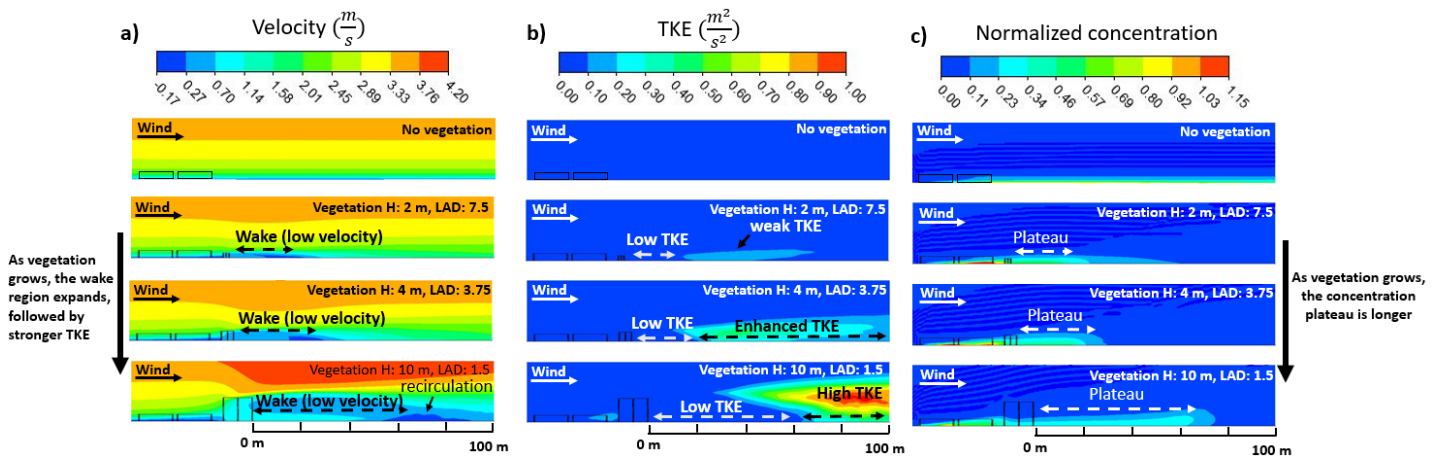
322 2.6 Pollutant concentration evaluation criteria

323 To assess the different vegetation barrier scenarios, the downwind pollutant concentration was
324 averaged over a height of 2 m, covering human breathing height. The spatial decay of concentration
325 was evaluated for 100 m starting behind the barrier (Figures 4b and 5), since pollutant reduction
326 within 100 m is necessary for communities living near roads and exposed to elevated pollutant
327 concentrations. In addition, after 100 m, the pollutant reduction of many vegetation barrier designs is
328 similar. Another metric considered was the average concentration for the 100 m region downwind of
329 the barrier, which can reflect the overall reduction by the barrier. To display the relative reduction in
330 comparison to having no vegetation, the pollutant concentrations have been normalized by the no
331 barrier concentrations at each respective wind speed.

332 3 Results and Discussion

333 3.1 Influence of vegetation growth on the barrier's physical dispersion mechanisms

334 To investigate how vegetation growth affects pollutant dispersion, it is important to first
 335 understand how the vegetative barrier alters airflow characteristics, such as velocity and turbulence.
 336 Figure 5 displays the velocity, TKE, and normalized concentration contours of the tracer gas for the
 337 vegetative barrier at various growth stages. The concentrations were normalized by the corresponding
 338 values in the no barrier case. Vegetation induces drag on the flow which slows down the velocity
 339 behind the barrier (wake region), but also creates a shear flow around it (low velocity behind the
 340 barrier, higher velocity above and around it as shown in Figure 5a). Furthermore, vegetation structures
 341 dissipate turbulence (Raupach and Thom, 1981; Finnigan, 2000; Poggi et al., 2004), which creates a
 342 region of low turbulence in the wake, followed by a region of high turbulence generated from the
 343 shear flow around the barrier as shown in Figure 5b. The concentration plateaus in the wake region
 344 due to reduced dispersion in the wake (low velocity and TKE), then it strongly decays due to enhanced
 345 TKE, velocity recirculation, and increased velocity after the wake (Figure 5c). Vegetation growth
 346 strongly impacts the aerodynamics of the barrier. As it grows taller and less dense, it will produce a
 347 longer wake region followed by higher turbulence due to enhanced shear flow (Figures 5a and 5b).
 348 Therefore, as the vegetation that forms the barrier matures, the concentration plateau extends for a
 349 longer distance before it decays (Figure 5c).

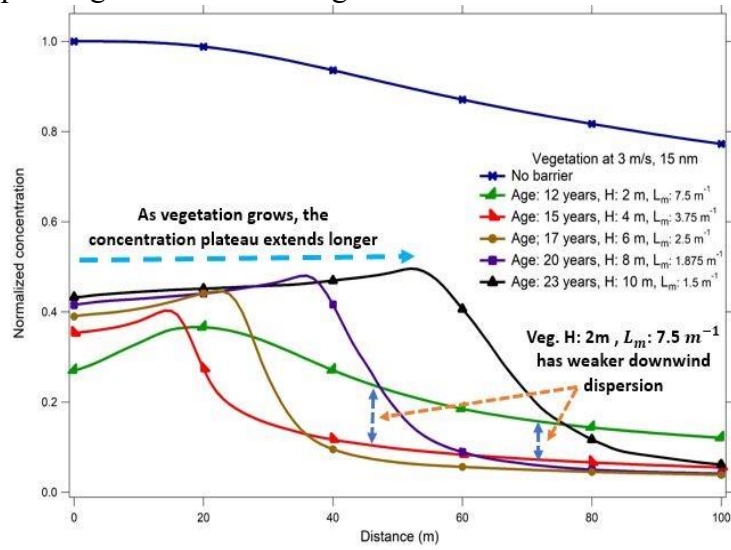


350 Figure 5: Contours for the no barrier and vegetation barriers at different growth stages with heights
 351 2, 4, and 10 m at a wind speed of 3 ms^{-1} a) Velocity; b) TKE; c) Concentration. As the vegetation
 352 grows, the wake region and the concentration plateau extend for a longer distance behind the
 353 barrier, and the TKE generated after the wake is enhanced.

354 3.2 Spatial decay of pollutant concentration at various growth stages

355 Figure 6 displays the normalized concentration versus distance from the barrier at different ages
 356 with heights of 2, 4, 6, 8 and 10 m for particle size 15 nm and wind speed 3 ms^{-1} . The concentrations
 357 were normalized by the no barrier concentration at the location immediately behind the barrier ($x =$
 358 0 m) (Figures 4b and 5). Figure S7 displays the spatial decay for particle size 253 nm. Particles of
 359 size 15 nm experience more reduction compared to those of 253 nm, due to enhanced deposition since
 360 15 nm particles have a higher deposition velocity than 253 nm particles. The downwind dispersion
 361
 362

363 for both particles is similar. Figure 6 indicates that the pollutant concentration initially plateaus for a
 364 distance roughly corresponding to the wake's length of each barrier.



365
 366 Figure 6: Normalized concentration versus distance from the barrier for the no barrier and vegetation
 367 at various ages with heights of 2, 4, 6, 8 and 10 m for particle size 15 nm and wind speed $3 ms^{-1}$.

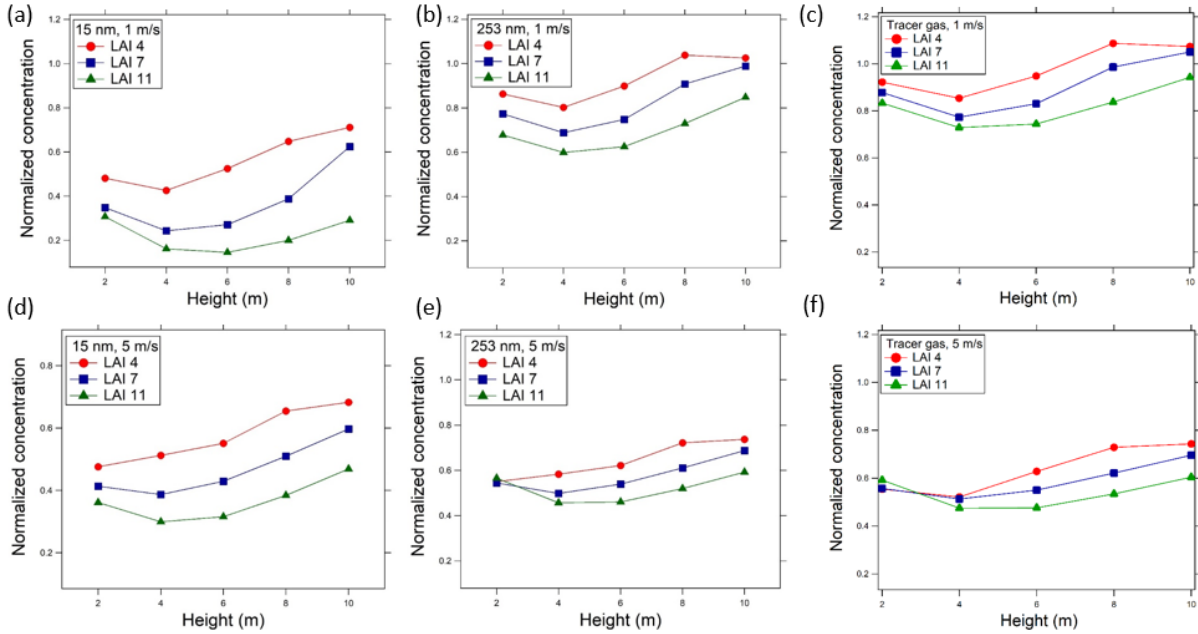
368 An extended concentration plateau region reduces the barrier's pollutant reduction capability
369 as the pollutant concentrations stagnate. Furthermore, the younger the vegetation, the shorter the
370 plateau region (Figure 6), however, the vegetation needs to mature to a certain height to generate
371 enough TKE to disperse the pollutants downwind of the barrier. Figure 6 shows that the pollutant
372 dispersion, due to the TKE, is weaker for the young vegetation (12 years, H: 2 m, L_m : $7.5 m^{-1}$),
373 compared to that of the mature vegetation barriers, as mature (taller) vegetation barriers generate
374 stronger TKE after the wake. Mature vegetation barriers (23 years, H: 10 m, L_m : $1.5 m^{-1}$) produced
375 more turbulence after the wake yet had similar downwind pollutant dispersion to that of vegetation
376 with heights of 4, 6, and 8 m (Figure 6). This indicates that the increased turbulence of mature
377 vegetation barriers did not enhance the reduction downwind of the barrier after a certain growth
378 threshold as the concentration becomes well-mixed. Vegetation growth influenced both the length
379 of the plateau region and the strength of the pollutant decay after the plateau.

380 An ideal barrier will have a short plateau (wake) region followed by a high TKE region to
381 disperse the pollutants. When the vegetation reaches a maturity level, where the height is
382 approximately 4 – 6 m, it generates enough TKE to disperse pollutants downwind, while having a
383 shorter plateau region compared to mature vegetation barriers (heights 8-10 m), resulting in ideal
384 pollutant reduction.

385

386 *3.3 Influence of vegetation growth on the reduction of particle sizes 15, 253 nm, and tracer gas* 387 *at extreme wind speeds*

388 Pollutant deposition by the vegetative barrier is particle-size dependent. Particles of size 15 nm
389 experience deposition dominated reduction, while particles of size 253 nm experience dispersion
390 dominated reduction. The velocities evaluated in this study ranged from 1 – $5 ms^{-1}$, and the extreme
391 reduction behavior occurred at either wind speeds of 1 or $5 ms^{-1}$, depending on the particle size,
392 as discussed later in Section 3.4. An ideal barrier will reduce the concentrations for both particle
393 sizes and wind speeds. Figure 7 shows the normalized average concentration over the 100 m
394 downwind region for particle sizes 15, 253 nm, and tracer gas at wind speeds 1 and $5 ms^{-1}$ for the
395 vegetation barrier at varying ages and LAI. The tracer gas concentration is slightly higher than
396 particle size 253 nm since that particle size experiences the least deposition.



397
 398 Figure 7: Average concentration over 100 m region downwind of the barrier and height 0 to 2 m,
 399 for vegetation barriers at varying ages and LAIs, normalized by the no barrier cases at each wind
 400 speed. a) 15 nm, 1 ms^{-1} ; b) 253 nm, 1 ms^{-1} ; c) Tracer gas, 5 ms^{-1} ; d) 15 nm, 5 ms^{-1} ; e) 253 nm, 5
 401 ms^{-1} ; f) Tracer gas, 5 ms^{-1} .

402
 403 When the vegetation grows to a height of 4 m, the lowest concentrations were observed as
 404 compared to other vegetation barrier heights, when considering different ages, LAI, particle sizes,
 405 and wind speeds (Figure 7). This trend was also observed when the concentration was averaged
 406 over heights 0 to 3 m and 0 to 4 m (Figures S8 and S9) which ensure that the results were not
 407 sensitive to the evaluation criteria chosen, averaging over a height 0 to 2 m. Figures 7a and 7d
 408 show that vegetation with height of 4 m had the most reduction for particle size 15 nm which is
 409 driven by deposition. Similarly, for particle size 253 nm, where reduction is dominated by the
 410 barrier's dispersion, when the barrier matures to a height of 4 m it has the most reduction compared
 411 to other barriers. That is due to a shorter wake region followed by enhanced TKE that strongly
 412 disperses the pollutants as highlighted in previous sections. While the overall reduction will
 413 depend on the particle size, LAI and wind speed, for dense vegetation LAI 11, a 4 m tall barrier
 414 can result in twice as much reduction compared to 2 or 10 m tall barriers for wind speed 1 m/s and
 415 particle size 15 nm or 17-23% percent reduction for wind speed 5 m/s and particle size 253 nm. It
 416 is important to note that for higher LAI values (7-11), which represent denser vegetation, the 6 m
 417 barrier resulted in similar reduction compared to the 4 m barrier. Since denser vegetation promote
 418 pollutant reduction, a 6 m tall vegetation barrier can also be an ideal vegetation barrier. A 6 m tall
 419 barrier could be beneficial especially for highways dominated by trucks, where the emission source
 420 is elevated, to ensure that the plume goes through the vegetation. Figure 7 highlights that a barrier,
 421 with height of 4-6 m, is optimal when accounting for both deposition and dispersion effects since
 422 it results in the most reduction across various LAI values, both particle sizes, and wind speeds.

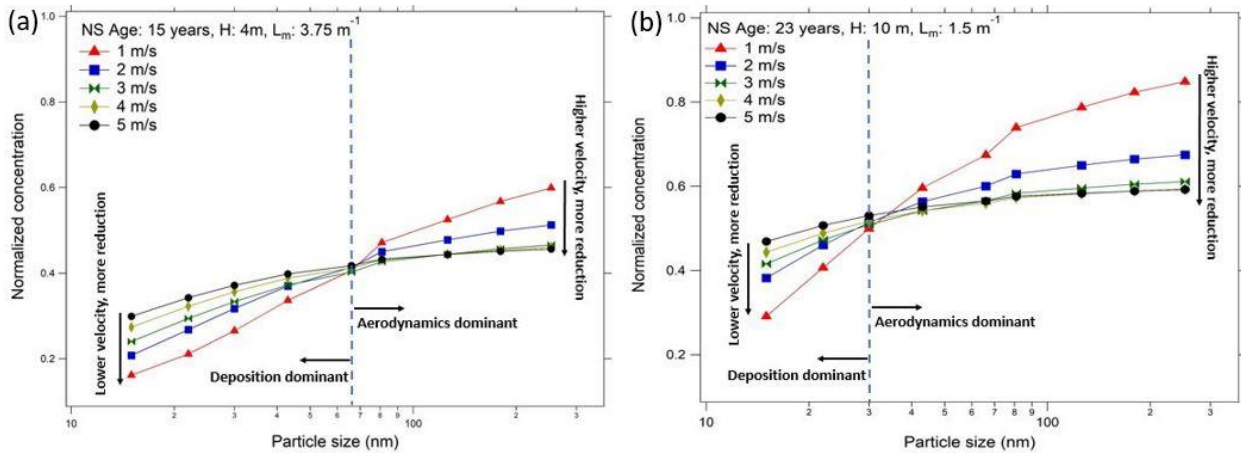
423 3.4 Impact of vegetation growth on average concentration (100m region) for various wind
 424 speeds and particle sizes

425 Whether pollutant reduction by the barrier will be dominated by deposition or downwind
 426 dispersion (driven by the aerodynamics of the barrier) depends on the wind speed, particle size,
 427 and vegetation barrier maturity. To explore these effects, Figure 8 displays average downwind
 428 concentrations over the 100 m region for vegetation barriers of different maturity levels (heights 4
 429 and 10 m) for different particle sizes and wind speed conditions. The concentration was normalized
 430 by the no barrier concentration at each respective wind speed.

431 For the vegetation height of 4 m and L_m 3.75 m^{-1} (Figure 8a), particles greater than 70 nm
 432 experience more reduction at increasing wind speeds, however, that effect becomes minimal at the
 433 highest wind speeds. For particle sizes greater than 70 nm, deposition effects are not dominant, but
 434 rather the downwind dispersion of the particles results in concentration reduction, which is
 435 enhanced at higher wind speeds due to higher TKE generation by the barrier (Figure S10). On the
 436 other hand, for particles less than 70 nm, deposition is more effective and at lower wind speeds,
 437 the particles spend more time within the vegetation barrier (increased residence time) which
 438 enhances reduction due to deposition. Figure 8b shows that for mature vegetation barriers (Age:
 439 23 years, H: 10 m, L_m : 1.5 m^{-1}), the critical particle size at which the dispersion and deposition
 440 effects are dominant occurs at a particle size of 30 nm.

441 While the physical growth of the vegetation can be captured in terms of height and width, hence
 442 particles spend more time within the vegetation, a reduced LAD impacts both the deposition and
 443 aerodynamics of the barrier. The study findings indicate that the reduced LAD results in less
 444 particle deposition resulting in a shift of particle size. The maturity of the vegetative barrier affects
 445 the critical particle size at which the effects of either vegetation deposition or dispersion dominate;
 446 thus, a very important parameter accounting for pollutant reductions.

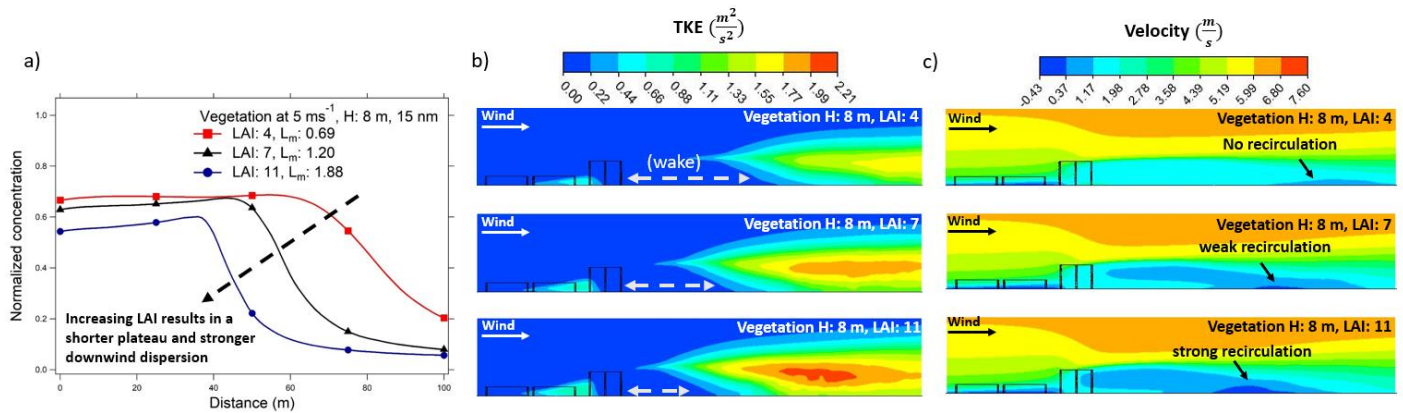
447



448 Figure 8: Average concentrations over 100 m region behind the barrier for various particle sizes
 449 and wind speeds for vegetation barriers at two different ages. The concentrations were
 450 normalized by the no barrier concentrations at the respective wind speeds, a) Vegetation age: 15
 451 years, height: 4 m, L_m 3.75 m^{-1} ; b) Vegetation age: 23 years, height: 10 m, L_m : 1.5 m^{-1} .
 452
 453

454 3.5 Influence of LAI, vegetation species, and LAD profile on pollutant reduction

455 Figure 7 highlighted an important trend that vegetation with a higher LAI (denser vegetation)
 456 will further increase pollutant reduction. Denser vegetation have a shorter wake region and
 457 generate higher turbulence downwind of the barrier (Figure 9b), thus promoting pollutant
 458 dispersion as highlighted in Figures 9a. While highly porous vegetation does not generate
 459 recirculation behind the barrier, denser vegetation produces a ‘detached recirculation’ (Larsen et
 460 al., 1999), i.e., occurring further downwind of the barrier after the wake (Figure 9c). The presence
 461 of a detached recirculation behind dense vegetation has also been reported in other studies
 462 (Cassiani et al., 2008; Detto et al., 2008; Ghasemian et al., 2017). For denser vegetation, not only
 463 does the recirculation strength increases, but also it occurs at a distance closer to the barrier because
 464 of a shorter wake region (Figure 9c), enhancing early pollutant dispersion.
 465
 466



467
 468 Figure 9: a) Normalized concentrations versus distance from the barrier for vegetation at height 8
 469 m with different LAI reflecting species with varying densities; b) and c) TKE and velocity
 470 contours for vegetation at height 8 m and velocity 5 ms⁻¹, vegetation with higher LAI generates
 471 higher TKE and have a shorter wake.
 472

473 High LAD vegetation has an increased surface area for particles to settle on, enhancing
 474 deposition compared to vegetation with a lower LAD. In addition, denser vegetation induces more
 475 drag on the flow, resulting in lower velocity within the canopy and hence increased residence time
 476 for particles, which also promotes deposition. Urban planners will not only benefit from
 477 maintaining the barrier at optimal height, but also selecting denser species at the initial planting
 478 phase can enhance the overall pollutant reduction of the barrier initially and over time. We also
 479 investigated the influence of the LAD profile shape on pollutant reduction. While the LAD profile
 480 for conifers vegetation was used in this study, four simulations were conducted with a uniform
 481 LAD profile to understand its impact on pollutant reduction. The profile shape had little impact on
 482 the downwind dispersion of pollutants; however, there were some differences for deposition
 483 dominated scenarios. Overall, the findings in this paper with regards to vegetation growth were
 484 not sensitive to this as highlighted in Section S7 of the supporting information (SI).

4853.6 Recommendations

486 This study highlights a few recommendations that urban planners should consider when
487 implementing vegetation barriers to improve air quality at sites experiencing high pollution levels
488 from traffic.

489 First, urban planners need to consider the vegetation growth rate and maintenance requirements
490 so that they can actively sustain vegetation barriers to an ideal height and achieve optimal post-
491 planting pollutant reduction. According to the American Conifer Society (ACS), conifers species
492 can be split into four size categories that are characterized by the following growth rates per year:
493 miniature ($< 2.5\text{ cm}$), dwarf ($2.5 - 15\text{ cm}$), intermediate ($15 - 30\text{ cm}$), and large ($> 30\text{ cm}$).
494 Furthermore, some conifers species are easier to control and prune relative to others. For example,
495 the ACS lists that yews and hemlocks are the easiest to control, and that firs, cedars, spruce and
496 Douglas firs are simple to manage. Additionally, pines require more care when pruning, and
497 junipers, arborvitae and false cypress are challenging to maintain at a particular size. Factors such
498 as the local climate will influence the vegetation species chosen and how fast it will grow,
499 therefore, stakeholders should select vegetation species that are manageable to prune logistically
500 and temporally given the growth rate of the conifer species they chose for their site.

501 Second, dense vegetation with high LAI values should be chosen as they are more effective at
502 pollutant reduction due to enhanced deposition and pollutant dispersion downwind of the barrier.

503 Third, the implemented vegetation barrier height should be around 4 to 6 m to promote
504 pollutant reduction. However, if that is not possible due to factors such as cost or geographical
505 compatibility, at a minimum the vegetation chosen should have matured to their peak LAI which
506 depends on the species. For example, Norway spruce reaches its peak LAI at ages between 10-15
507 years and at heights between 1.5-2 m. Using younger vegetation, before they reach their peak LAI,
508 is not ideal as they are still developing and hence have lower LAI values, and they might be too
509 short that pollutants can pass above them unobstructed.

510 Fourth, by identifying the ideal barrier height in the range of 4 to 6 m, urban planners can
511 determine the planting space between trees that will allow for the optimal growth of the barrier.

512 Finally, in addition to maintaining the barrier at optimal height, other studies have shown that
513 combining vegetation with either low-cost impermeable solid structures (LISS), sound walls, or
514 other vegetation species (low thick bushes) can further enhance pollutant reduction (Tong et al.
515 2016, Deshmukh et al. 2019, Hashad et al. 2020). This should be implemented, when possible,
516 even if the barrier is maintained at an ideal height. In particular, that could be beneficial when the
517 vegetation is still developing or if it is too tall to further enhance its pollutant reduction capability.

518 For sites with currently existing vegetation, if the barrier is shorter than the optimal height, the
519 vegetation should be nurtured to reach, and then subsequently maintained, at the recommended
520 height. If it is taller than optimal height, the vegetation should be pruned and maintained at the
521 recommended height if feasible. However, in some sites, pruning to optimal height might be
522 challenging, because either the existing vegetation is too tall, or the species is difficult to prune. In
523 that case, efforts should be made to curb its growth and its pollutant reduction capability can be
524 further promoted by combining it with either solid or vegetation structures.

525 *3.7 Limitations*

526 The pollutant reduction of any vegetation barrier will depend on local conditions, such as
527 atmospheric stability, traffic density and speed, vehicle fleet mix, vehicle induced turbulence, the
528 presence of buildings, roadway configuration and wind direction. While the impact of all these
529 factors were not considered in this study, several key factors likely to dominate the effectiveness
530 of vegetation barriers in reducing local air pollution including wind speed, vegetation dimensions
531 and LAI were explored. Furthermore, the pollutant release height in this study was 3 m which
532 might not fully reflect truck emissions which tend to be at a slightly higher height of approximately
533 4 m. In addition, all the vegetation barriers considered in this study were implemented close to the
534 highway (5 m distance between the traffic zone and the beginning of the barrier). In addition, the
535 barrier's dimensions, at the different ages considered in this study assumed optimal growth so no
536 gaps existed within the barrier. Ensuring the vegetative barrier is dense with no gaps will rely on
537 the initial plant size, spacing between the planted trees, soil quality to allow for healthy growth,
538 and maintenance and pruning of the barrier after planting. Finally, more field evaluations of the
539 simulation results will enhance the robustness of our recommendations.

540 **4 Conclusion**

541 This paper analyzes how vegetation growth impacts its physical (dimensions) and ecological
542 (density) attributes based on various field measurement studies. Then, we conducted 75 LES
543 simulations to investigate how the growth of roadside vegetation barriers influences TRAP
544 mitigation in near-road environments. Young vegetation barriers (12 years, H: 2 m) provided less
545 downwind pollutant dispersion as a result of reduced turbulence generation compared to mature
546 (taller) vegetation. Mature vegetation (23 years, H: 10 m) created a longer wake region,
547 characterized by low velocity and turbulence, which inhibited pollutant dispersion.

548 The optimum effectiveness of the barrier to reduce TRAP in a near-road environment was for
549 a vegetation barrier of 4-6 m in height, since it generated sufficient TKE to efficiently disperse
550 pollutants downwind, had a small wake region, and enhanced deposition. The influence of
551 deposition or dispersion as the dominant factor attributed to pollutant reduction using the
552 vegetation barrier varied depending on wind speed ($1-5\text{ ms}^{-1}$), particle size (15 or 253 nm), and
553 the physical (height) and ecological (LAI) attributes of the vegetation. When the barrier matures
554 to 4-6 m, this represents the optimal height to reduce near-road pollutants through both deposition
555 and dispersion, regardless of LAI characteristics. This study demonstrates that as vegetation grows,
556 there is a dynamic and non-linear response in terms of pollutant reduction.

557

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